

## Section 3.4: Complex eigenvalues

### Case II: $\lambda_1 = \lambda_2 \in \mathbb{C}$ and $\lambda_2 = \overline{\lambda_1}$

To shorten the notation, **write  $\lambda$  instead of  $\lambda_1$** .

So, we are supposing that  $A$  has two complex conjugate (and not real) eigenvalues:

$$\lambda = \mu + i\nu \quad \text{and} \quad \overline{\lambda} = \mu - i\nu$$

where  $\mu, \nu$  are real numbers.

In particular:  $\lambda$  and  $\overline{\lambda}$  are distinct and non-zero.

- Eigenvectors  $\mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$  associated with complex eigenvalues have usually complex components  $v_1 = a_1 + ib_1, v_2 = a_2 + ib_2$  (with  $a_1, b_1, a_2, b_2 \in \mathbb{R}$ ).
- If  $\mathbf{v} = \mathbf{a} + i\mathbf{b} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + i \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$  is an eigenvector of eigenvalue  $\lambda$ , i.e.  $A\mathbf{v} = \lambda\mathbf{v}$  then  $\overline{\mathbf{v}} = \mathbf{a} - i\mathbf{b} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} - i \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$  is eigenvector of eigenvalue  $\overline{\lambda}$ , i.e.  $A\overline{\mathbf{v}} = \overline{\lambda}\overline{\mathbf{v}}$ .
- Two linearly independent solutions of  $\mathbf{x}' = A\mathbf{x}$  are
$$\mathbf{x}_1(t) = e^{\lambda t}\mathbf{v} = e^{(\mu+i\nu)t}\mathbf{v} \quad \text{and} \quad \mathbf{x}_2(t) = e^{\overline{\lambda}t}\overline{\mathbf{v}} = e^{(\mu-i\nu)t}\overline{\mathbf{v}}$$

We have two linearly independent **complex-valued** solutions of  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ , namely

$$\mathbf{x}_1(t) = e^{\lambda t} \mathbf{v} = e^{(\mu+i\nu)t} \mathbf{v} \quad \text{and} \quad \mathbf{x}_2(t) = e^{\bar{\lambda}t} \bar{\mathbf{v}} = e^{(\mu-i\nu)t} \bar{\mathbf{v}}$$

We want to have two **real-valued** solutions.

- $\mathbf{x}_2(t) = \overline{\mathbf{x}_1(t)}$  [because  $\bar{\bar{z}} = z$  for  $z, s \in \mathbb{C}$ ].
- Linear combinations of solutions are solutions (principle of superposition): since  $\mathbf{x}_1$  and  $\mathbf{x}_2 = \overline{\mathbf{x}_1}$  are solutions, so are

$$\mathbf{u} = \frac{1}{2} \mathbf{x}_1 + \frac{1}{2} \mathbf{x}_2 = \frac{\mathbf{x}_1 + \overline{\mathbf{x}_1}}{2} = \operatorname{Re} \mathbf{x}_1$$

and

$$\mathbf{w} = \frac{1}{2i} \mathbf{x}_1 - \frac{1}{2i} \mathbf{x}_2 = \frac{\mathbf{x}_1 - \overline{\mathbf{x}_1}}{2i} = \operatorname{Im} \mathbf{x}_1$$

- $\mathbf{u} = \operatorname{Re} \mathbf{x}_1$  and  $\mathbf{w} = \operatorname{Im} \mathbf{x}_1$  are real-valued solutions.
- **Fact:**  $\mathbf{u}$  and  $\mathbf{w}$  are linearly-independent.

**Conclusion:** The general solution of  $\mathbf{x}' = \mathbf{A}\mathbf{x}$  is:

$$\mathbf{x}(t) = C_1 \mathbf{u}(t) + C_2 \mathbf{w}(t)$$

where  $C_1, C_2$  are constants.

### Example:

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*General solution:*  $\mathbf{x}(t) = C_1 \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + C_2 \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$ , where  $C_1, C_2$  are constants and  $t \in \mathbb{R}$ .

- Find the solution of the IVP for  $\mathbf{x}' = A\mathbf{x}$  with initial condition  $\mathbf{x}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ .

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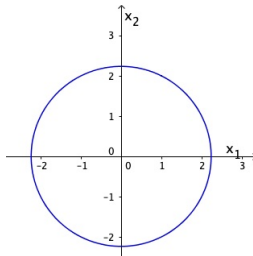
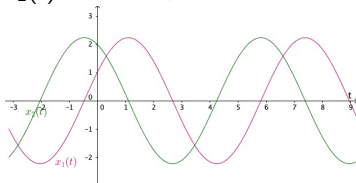
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- Find the solution of the IVP for  $\mathbf{x}' = A\mathbf{x}$  with initial condition  $\mathbf{x}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ .

$$x_1(t) = \cos t + 2 \sin t$$

$$x_2(t) = -\sin t + 2 \cos t$$



The trajectory in the phase plane is a circle.

## Explicit expressions of $\mathbf{u}$ and $\mathbf{w}$ (general case):

- $\mathbf{u}(t) = \operatorname{Re} \mathbf{x}_1(t) = \operatorname{Re} \left( e^{(\mu+i\nu)t} \mathbf{v} \right)$

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For $z, s \in \mathbb{C}$ :	$\operatorname{Re}(zs) = \operatorname{Re} z \operatorname{Re} s - \operatorname{Im} z \operatorname{Im} s$
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- For  $\mu, \nu, t \in \mathbb{R}$ :  $e^{(\mu+i\nu)t} = e^{\mu t} e^{i\nu t} = e^{\mu t} (\cos(\nu t) + i \sin(\nu t))$ .

Hence:

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- For  $\mathbf{v} = \mathbf{a} + i\mathbf{b} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + i \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$ , we have  $\operatorname{Re} \mathbf{v} = \mathbf{a}$  and  $\operatorname{Im} \mathbf{v} = \mathbf{b}$ .

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**Conclusion:**

$$\mathbf{u}(t) = e^{\mu t} [\cos(\nu t) \mathbf{a} - \sin(\nu t) \mathbf{b}]$$

$$\mathbf{w}(t) = e^{\mu t} [\cos(\nu t) \mathbf{b} + \sin(\nu t) \mathbf{a}].$$

# Behavior of the solutions

Since  $\det(A) = \lambda\bar{\lambda} \neq 0$

$$\mathbf{x}_{\text{eq}} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

is the unique equilibrium (or critical) point.

It corresponds to the origin  $(0, 0)$  of the phase plane

The solutions

$$\mathbf{u}(t) = e^{\mu t}[\cos(\nu t)\mathbf{a} - \sin(\nu t)\mathbf{b}]$$

$$\mathbf{w}(t) = e^{\mu t}[\cos(\nu t)\mathbf{b} + \sin(\nu t)\mathbf{a}].$$

have an oscillatory behavior as functions of  $t$ .

The nature of the oscillation depends on  $\mu = \text{Re } \lambda$ .

$$\mathbf{u}(t) = e^{\mu t}[\cos(\nu t)\mathbf{a} - \sin(\nu t)\mathbf{b}]$$

$$\mathbf{w}(t) = e^{\mu t}[\cos(\nu t)\mathbf{b} + \sin(\nu t)\mathbf{a}].$$

- $\mu = 0$ , i.e.  $\lambda = i\nu$ :

$\mathbf{u}(t)$  and  $\mathbf{v}(t)$  are periodic function of  $t$  of period  $T = \frac{2\pi}{\nu}$ .

*In the phase plane:*

The trajectories are ellipses.

The origin  $(0, 0)$  is called a **center** and it is said to be **stable**.

- $\mu < 0$ :

As functions of  $t$ , the amplitude of the oscillations of  $\mathbf{u}(t)$  and  $\mathbf{v}(t)$  decays exponentially.

*In the phase plane:*

The trajectories spiral around  $(0, 0)$  and approach  $(0, 0)$  at  $t \rightarrow +\infty$ .

The origin  $(0, 0)$  is called a **spiral sink** and it is said to be **asymptotically stable**.

- $\mu > 0$ :

As functions of  $t$ , the amplitude of the oscillations of  $\mathbf{u}(t)$  and  $\mathbf{v}(t)$  grows exponentially.

*In the phase plane:*

The trajectories spiral out of  $(0, 0)$  as  $t$  increases.

The origin  $(0, 0)$  is called a **spiral source** and it is said to be **unstable**.