

## Section 7.3: Competing species

### Main Topics:

- **Logistic equations,**
- **Mathematical models of competitive situations:**  
two populations competing for scarce resources.

*Examples:* two species competing for food supplies, competitions in a same economic market

- **Long time behavior of solutions near the critical solutions**  
Method: linear approximations.

# A logistic model for competing species

Let  $x(t)$  and  $y(t)$  denote the size at time  $t$  of two interacting or competing populations for a common food or resource.

We will consider the following modelization (based on the logistic equation):

$$\frac{dx}{dt} = x(\epsilon_1 - \sigma_1 x - \alpha_1 y)$$

$$\frac{dy}{dt} = y(\epsilon_2 - \sigma_2 y - \alpha_2 x)$$

where

- $\epsilon_1$  and  $\epsilon_2$  are the **growth rates** of the two populations,
- $\epsilon_1/\sigma_1$  and  $\epsilon_2/\sigma_2$  are their **saturation levels**,
- $\alpha_1$  measures the **interference** of the species  $y$  with the species  $x$ ,
- $\alpha_2$  measures the **interference** of the species  $x$  with the species  $y$ .

### Example:

- We want to study the qualitative behavior of the solutions of the competing system

$$\frac{dx}{dt} = x(1 - x - y)$$

$$\frac{dy}{dt} = y(0.75 - y - 0.5x)$$

- The critical points of the system are:

$(0, 0)$ ,  $(0, 0.75)$ ,  $(1, 0)$  and  $(0.5, 0.5)$

Critical points and direction field for the system

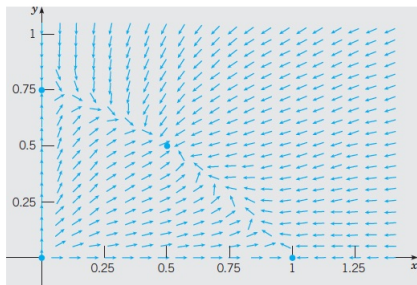


FIGURE 7.3.1 Critical points and direction field for the system (3).

For the above system, the functions

$$F(x, y) = x(1 - x - y) \text{ and } G(x, y) = y(0.75 - y - 0.5x)$$

have continuous partial derivatives of any order (in particular, up to order 2).

The system is almost linear in the neighborhood of any of the critical points.

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$$\mathbf{J} = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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The linear approximation of the system at the critical point  $(X, Y)$  is

$$\frac{d}{dt} \begin{pmatrix} u \\ w \end{pmatrix} = \mathbf{J}(X, Y) \begin{pmatrix} u \\ w \end{pmatrix}$$

where  $u = x - X$  and  $w = y - Y$ .

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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**Case of (0, 0):**

This solution corresponds to the extinction of both species.



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The approximating linear system is

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0.75 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

The eigenvalues are  $\lambda_1 = 1$  and  $\lambda_2 = 0.75$ .

The critical point (0, 0) is an unstable node of both the linear and the nonlinear systems.

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The general (vector) solution of the linear system is

$$\begin{pmatrix} x \\ y \end{pmatrix} = c_1 e^t \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{0.75t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

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If  $c_2 \neq 0$ :

$$\begin{pmatrix} x \\ y \end{pmatrix} \sim c_2 e^{0.75t} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad (t \rightarrow -\infty)$$

So: in the neighborhood of the origin all trajectories are tangent to the  $y$ -axis, except for one trajectory that lies on the  $x$ -axis.

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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**Case of (0, 0.75):** In this case, the species  $x$  is extinct and  $y$  survives.

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

**Case of (0, 0.75):** In this case, the species  $x$  is extinct and  $y$  survives.

The approximate linear system near this critical point is:

$$\frac{d}{dt} \begin{pmatrix} u \\ w \end{pmatrix} = \begin{pmatrix} 0.25 & 0 \\ -0.375 & -0.75 \end{pmatrix} \begin{pmatrix} u \\ w \end{pmatrix}$$

where  $u = x$  and  $w = y - 3/4$ .

The eigenvalues are  $\lambda_1 = 0.25$  and  $\lambda_2 = -0.75$ .

The critical point (0, 0.75) is a saddle point and therefore it is unstable for both systems.

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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The eigenvalues are  $\lambda_1 = 0.25$  and  $\lambda_2 = -0.75$ .

The critical point (0, 0.75) is a saddle point and therefore it is unstable for both systems.

The general (vector) solution of the linear system is

$$\begin{pmatrix} u \\ w \end{pmatrix} = c_1 e^{0.25t} \begin{pmatrix} 8 \\ -3 \end{pmatrix} + c_2 e^{-0.75t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

If  $c_1 = 0$ , then there is one pair of trajectories (corresponding to  $c_2 e^{-0.75t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ ) approaching the critical point along the  $y$ -axis for  $t \rightarrow \infty$ .

If  $c_2 = 0$ , then there is one pair of trajectories (corresponding to  $c_1 e^{0.25t} \begin{pmatrix} 8 \\ -3 \end{pmatrix}$ ) departing tangent to the line with slope  $-3/8$ .

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$



$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

**Case of (1, 0):** In this case, the species  $x$  survives and the species  $y$  does not.

It is similar to the previous case.

The approximating linear system is

$$\frac{d}{dt} \begin{pmatrix} u \\ w \end{pmatrix} = \begin{pmatrix} -1 & -1 \\ 0 & 0.25 \end{pmatrix} \begin{pmatrix} u \\ w \end{pmatrix}$$

where  $u = x - 1$  and  $w = y$ .

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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where  $u = x - 1$  and  $w = y$ .

The eigenvalues are  $\lambda_1 = -1$  and  $\lambda_2 = 0.25$ .

The critical point (1, 0) is a saddle point and it is unstable for both systems.

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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where  $u = x - 1$  and  $w = y$ .

The eigenvalues are  $\lambda_1 = -1$  and  $\lambda_2 = 0.25$ .

The critical point (1, 0) is a saddle point and it is unstable for both systems.

The general (vector) solution of the linear system is

$$\begin{pmatrix} u \\ w \end{pmatrix} = c_1 e^{-t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{0.25t} \begin{pmatrix} 4 \\ -5 \end{pmatrix}$$

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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The general (vector) solution of the linear system is

$$\begin{pmatrix} u \\ w \end{pmatrix} = c_1 e^{-t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{0.25t} \begin{pmatrix} 4 \\ -5 \end{pmatrix}$$

One pair of trajectories approaches the critical point along the  $x$ -axis, another leaves the critical point tangent to the line of slope  $-5/4$ . All other trajectories depart from a neighborhood of (1, 0).

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

**Case of (0.5, 0.5):** This critical point corresponds to the coexistence of both species.

$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

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The approximating linear system is

$$\frac{d}{dt} \begin{pmatrix} u \\ w \end{pmatrix} = \begin{pmatrix} -0.5 & -0.5 \\ -0.25 & -0.5 \end{pmatrix} \begin{pmatrix} u \\ w \end{pmatrix}$$

where  $u = x - 0.5$  and  $w = y - 0.5$ .

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where  $u = x - 0.5$  and  $w = y - 0.5$ .

The eigenvalues are  $\lambda_1 = \frac{-2+\sqrt{2}}{4}$  and  $\lambda_2 = \frac{-2-\sqrt{2}}{4}$ .

The critical point (0.5, 0.5) is an asymptotically stable node for both systems.



$$\mathbf{J}(\mathbf{x}, \mathbf{y}) = \begin{pmatrix} 1 - 2x - y & -x \\ -0.5y & 0.75 - 2y - 0.5x \end{pmatrix}$$

**Case of (0.5, 0.5):** This critical point corresponds to the coexistence of both species. The approximating linear system is

$$\frac{d}{dt} \begin{pmatrix} u \\ w \end{pmatrix} = \begin{pmatrix} -0.5 & -0.5 \\ -0.25 & -0.5 \end{pmatrix} \begin{pmatrix} u \\ w \end{pmatrix}$$

where  $u = x - 0.5$  and  $w = y - 0.5$ .

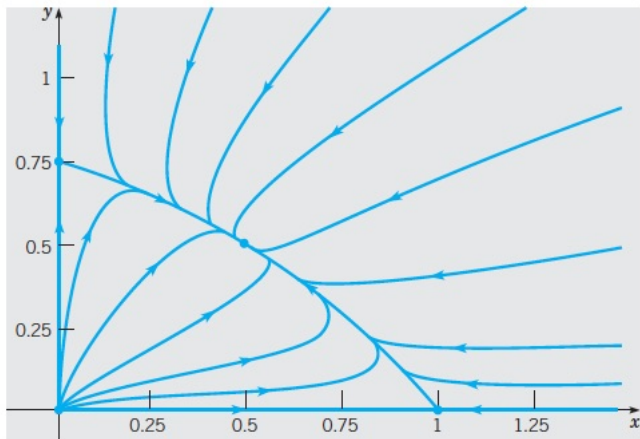
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The critical point (0.5, 0.5) is an asymptotically stable node for both systems.

The general (vector) solution of the linear system is:

$$\begin{pmatrix} x \\ y \end{pmatrix} = c_1 e^{(\frac{-2+\sqrt{2}}{4})t} \begin{pmatrix} \sqrt{2} \\ -1 \end{pmatrix} + c_2 e^{(\frac{-2-\sqrt{2}}{4})t} \begin{pmatrix} \sqrt{2} \\ 1 \end{pmatrix}$$

All trajectories approach the critical point as  $t \rightarrow +\infty$ . One pair of trajectories approaches the critical point along the line with slope  $\sqrt{2}/2$ , all others along the line with slope  $-\sqrt{2}/2$ .



**FIGURE 7.3.2** A phase portrait of the system (3).